**Continual learning using dendritic modulations on** view-invariant feedforward weights Viet Anh Khoa Tran, Emre Neftci, Willem A. M. Wybo Neuromorphic Software Ecosystems (PGI-15), Forschungszentrum Jülich, Germany.



## **Visual Processing in Biological Brains**

- Visual processing in the brain consists of a rapid feedforward pass generating generic task-independent features, while complex visual tasks require **top-down** inputs (A, [1]).
- Comparatively longer-lasting top-down afferents impinging on dendritic branches have been proposed to dynamically reshape feedforward computation to solve new tasks (**B**, [2]).
- This kind of computation can be modeled as  $\sigma(\mathbf{g}_t \odot (\mathbf{W} \cdot \mathbf{x}) + \mathbf{b}_t).$



Β

### **Continual self-supervised learning retains class clusters**



 Newborn chicks reared in environments with smoothly moving visual objects develop view-invariant **recognition capabilities**, but are sensitive to view-changes when reared with temporally non-smoothly moving objects [3].



feedforward

### **Towards a Biologically Plausible Continual Learner**



performance (**A**, •: mean over per-task peaks).

However, task performance deteriorates as novel tasks are trained (bars: final mean-task performance).

learner () outperforms its frozen counterpart () on per-task peak

• Yet, this is not catastrophic forgetting. Evaluating with the k-nearest neighbor algorithm (kNN), the continual learner is close to its peak performance (B). We hypothesize that the continual learning retains clustered representations of prior tasks, but that they drift due to the continual learning. Thus, performance of the fixed linear readout, but not of kNN, deteriorates.

# **Recovering cluster readout by least-squares regression**

• During training of task *t*, we store *m* images per class via reservoir sampling  $(\mathbf{X}_t)$ . At the end of each session, we evaluate and store the logits of all memory samples of the current task, i.e.,

 $\mathbf{L}_t = \mathbf{R}_t f(\mathbf{X}_t).$ 



• At every training step, we perform readout restoration on all previous tasks via Tikhonov-regularized least-squares regression towards  $\mathbf{R}_t$ 

$$\min_{\mathbf{R}_t} \|\mathbf{R}_t f(\mathbf{X}_t) - \mathbf{L}_t\| + \lambda \|\mathbf{R}_t - \mathbf{R}_t^{\mathrm{curr}}\|^2.$$

- Contrastive self-supervised learning approaches ( $\mathcal{L}_{ssl}$ , **C**) approximate view-invariance by pulling together representations of distorted views of the same image, while repelling views of different images.
- Still, the theoretical optimum for solving classification tasks is obtained with the collapse phenomenon. We therefore introduce dendrite-inspired task-dependent modulations trained in a supervised fashion (**E**, **D**).
- A simple trick to completely avoid catastrophic forgetting is to freeze the task-shared weights ( current task (
- We furthermore investigate combining both  $\mathcal{L}_{ssl}$  and  $\mathcal{L}_{sup}$ , intuitively making the feedforward weights "task-aware" while avoiding catastrophic forgetting (

• With few samples, we are almost able to obtain kNN performance.

#### Task 2 Task 12 Task 7 All tasks 0.9 6.9 6.0 8 0.4 0.2 0 1000 250 750 1000 1000 algorithms epoch Introducing our readout restoration mechanism to all proposed algorithms, we show that continual self-supervised weights ( outperform frozen self-supervised ( ( ), while mostly avoiding catastrophic forgetting.

- Results suggest with task-agnostic weights, task-specific supervised modulations ( task performance, as they significantly outperform the unmodulated counterparts (
- With task-aware weights ( decreased. We hypothesize that the given setup (CIFAR-100 split into 20 random tasks) is too simple and the generated classification tasks have similar invariances.

# Conclusion

• Our work indicates that SSL could be an appropriate model for continual

### Task-agnostic weights require modulations

Ъд	weights $W$	$\frac{2}{2}$ weights $W$	$\frac{\sigma}{2}$ weights $W$	$\frac{1}{2}$ weights $W$
Su	readout, task 1	r/o, task 2	<sup>ਡ</sup> r/o, task 3	<sup>ਡ</sup> r/o, task 4
ssl D <sub>1</sub>	weights $W$			
n D <sub>1</sub>	readout, task 1	r/o, task 2	r/o, task 3	r/o, task 4
ssl D <sub>1</sub>	weights $W$			_
5	readout, task 1	പ്പ r/o, task 2	<mark>ര</mark> ് r/o, task 3	<mark>₁</mark> r/o, task 4
dns	$g_1,b_1$	$\frac{1}{2}$ $g_2, b_2$	$rac{d}{g}  g_3,  b_3$	$rac{d}{ds}$ $g_4, b_4$
ssl D <sub>1</sub>	weights $W$	$\frac{2}{g}$ weights $W$	$\frac{2}{3}$ weights $W$	$\frac{4}{2}$ weights $W$
nd D1	readout, task 1	r/o, task 2	م r/o, task 3	r/o, task 4
ssl D1	weights $W$	$\frac{2}{3}$ weights $W$	$\frac{c_{g}}{c_{g}}$ weights $W$	$\frac{P_{g}}{W}$ weights $W$
5	readout, task 1	് r/o, task 2	<mark>අ</mark> r/o, task 3	<mark>4</mark> r/o, task 4
dns	$g_1,b_1$	$\frac{1}{2}$ $g_2, b_2$	$\frac{d}{ds}$ $g_3, b_3$	${}^{rad}_{s}$ $g_4, b_4$
Dr Dr	weights $W$			Rel D4 Rel D4 W
õ	readout, task 1	ة r/o, task 2	r/o, task 3	r/o, task 4
D1 SS D4	weights $W$			
7 dns	readout, task 1	gr/o, task 2	r/o, task 3	r/o, task 4
	$g_1, b_1$	$g_2, b_2$	$g_3, b_3$	$g_4, b_4$
l 'p	pretraining' task ( $t=1$ )	t=2	t=3	t=4

D

Objectives

 $\mathcal{L}_{ ext{sup}} := \operatorname{CE}((\operatorname{readout} \circ f)(X_t; \ \Theta, \Psi_t) \| Y_t)$ 

 $\mathcal{L}_{\rm ssl} := {\rm BarlowTwins}((g_{\rm ssl} \circ f)([X'_t, X''_t]; \Theta, \varnothing))$ 

 $\mathcal{L}_{ ext{ssl}} + \lambda \cdot \mathcal{L}_{ ext{sup}}$ 

Algorithms

- supervised weights (baseline)
- task-agnostic ssl-weights, frozen
- L with modulations
- task-agnostic ssl-weights, continual
- L with modulations
- task-aware ssl-weights, continual
  - L with modulations

learning in the brain, as it can continuously incorporate new data while only minimally forgetting previously learning concepts.

Dendritically inspired modulations allow for optimally solving tasks on task-agnostic weights, which we consider more bioplausible than task-aware weights.

### References

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